

1/27


COMPUTATIONAL PREDICTION OF PROPELLANT REORIENTATION

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WASHINGTON UNIVERSITY

WORK SUPPORTED BY NASA LeRC
THROUGH GRANT NAG3-578



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	<p>OUTLINE</p>	<p>2/27</p>
<p>COMPUTATIONAL TECHNOLOGY</p> <ul style="list-style-type: none"> – SOLA FAMILY – UNIQUE FEATURES OF NASA–VOF2D <p>PROPELLANT REORIENTATION</p> <ul style="list-style-type: none"> – MOTIVATION – COMPUTATIONAL DETAILS – CODE VERIFICATION – PRELIMINARY RESULTS 		



NASA—VOF2D

DEVELOPED FOR LERC BY THE LOS ALAMOS SCIENTIFIC LABORATORY (LASL) AS PART OF AN ONGOING INTERAGENCY AGREEMENT.

GENERAL CAPABILITIES:

- TWO DIMENSIONAL (CARTESIAN OF CYLINDRICAL)
- VARIABLE MESH (ROWS & COLUMNS)
- EULERIAN FORMULATION
- STAGGERED GRID OF PRIMITIVE VARIABLES
- TRANSIENT LAMINAR HYDRODYNAMICS WITH A FREE SURFACE



4/27


UNIQUE FEATURES

SOLA: SOLUTION ALGORITHM

VOF: VOLUME-OF-FLUID METHOD

SURFACE TENSION MODEL

PARTIAL CELL BLOCKAGE

	REORIENTATION	5/27
<div data-bbox="344 451 401 1497" data-label="Section-Header"> <h1>PROPELLANT REORIENTATION</h1> </div> <div data-bbox="535 1441 582 1772" data-label="Section-Header"> <h2><u>MOTIVATION</u></h2> </div> <div data-bbox="614 461 713 1576" data-label="Text"> <p>DESIRE TO PREDICT PROPELLANT MOTION DURING IMPULSIVE SETTLING.</p> </div> <div data-bbox="962 1080 1008 1768" data-label="Section-Header"> <h2><u>POTENTIAL APPLICATIONS</u></h2> </div> <div data-bbox="1041 296 1248 1768" data-label="List-Group"> <ul style="list-style-type: none"> – CONSERVATION OF PROPELLANT IN NEW DESIGNS – MATCH EXISTING EQUIPMENT TO NEW APPLICATIONS – INVESTIGATE NOVEL APPROACHES </div>		

CODE VERIFICATION

COMPARE COMPUTATIONAL PREDICTIONS TO
EXPERIMENTAL DATA FOR SMALL SCALE TANKS.

6 CASES SELECTED FROM:

SUMNER, I.E.; LIQUID PROPELLANT REORIENTATION
IN A LOW-GRAVITY ENVIRONMENT.
NASA TM-78969, 1978

- DATA IS FROM LeRC ZERO-GRAVITY FACILITY
- CASES INCLUDE A RANGE OF TEST FLUIDS,
ACCELERATION LEVELS, GEYSER HEIGHTS, AND
TANK SHAPES
- A CORRELATION IS PROPOSED FOR PREDICTING
REORIENTATION PERFORMANCE.



CODE VERIFICATION

7/27

SUMMARY OF TEST CONDITIONS

TEST	TR	FR	FLUID	FL	AT	BO	GEYSER
5	2.0	2.25	ETHANOL	62	29.4	4.2	SMALL
1	1.65	4.0	TCTFE	71	16.7	3.9	SMALL
12	3.22	2.14	ETHANOL	71	10.8	4.0	NONE
6	2.0	2.25	ETHANOL	29	29.4	4.2	LARGE
7	2.0	2.25	METHANOL	51	29.4	4.1	MODERATE
8	2.0	2.25	METHANOL	33	29.4	4.1	LARGE

TR = TANK RADIUS (CM)

FR = FINENESS RATIO

FL = FILL LEVEL (%)

AT = TANK ACCELERATION (CM/SEC**2)

BO = BOND NUMBER

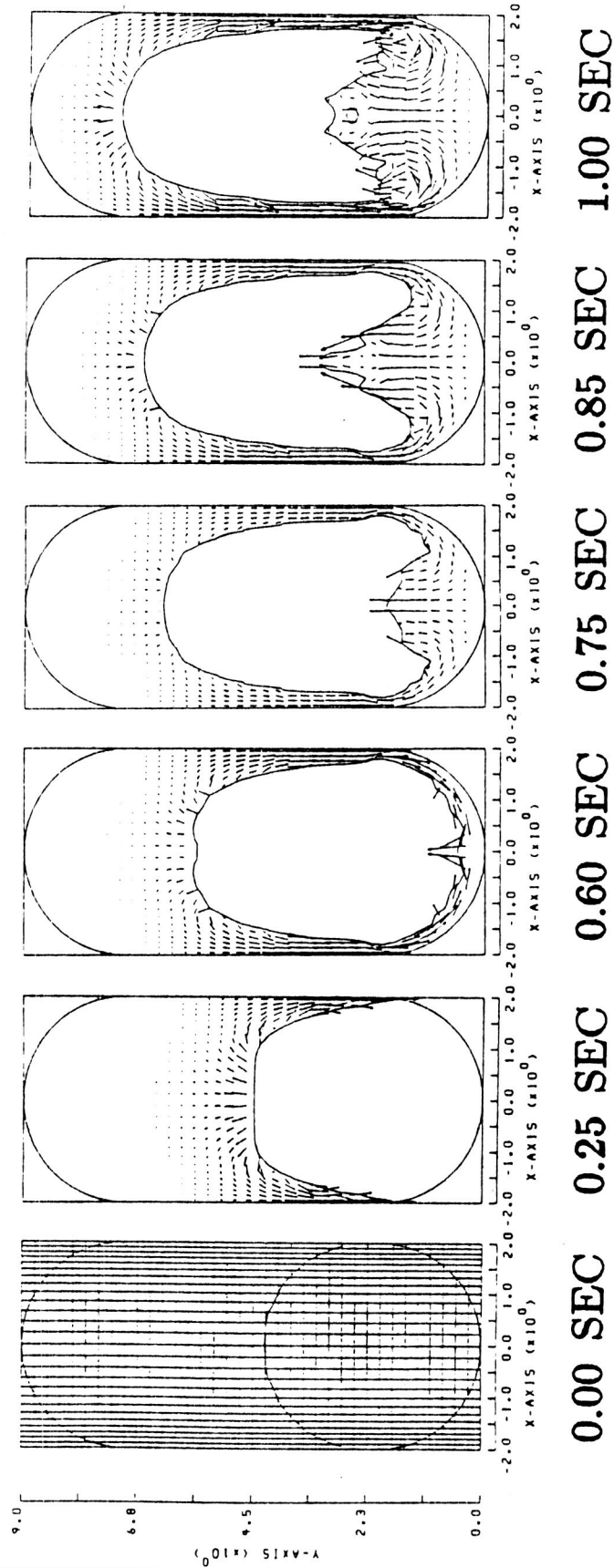
TCTFE = TRICHLOROTRIFLUOROETHANE



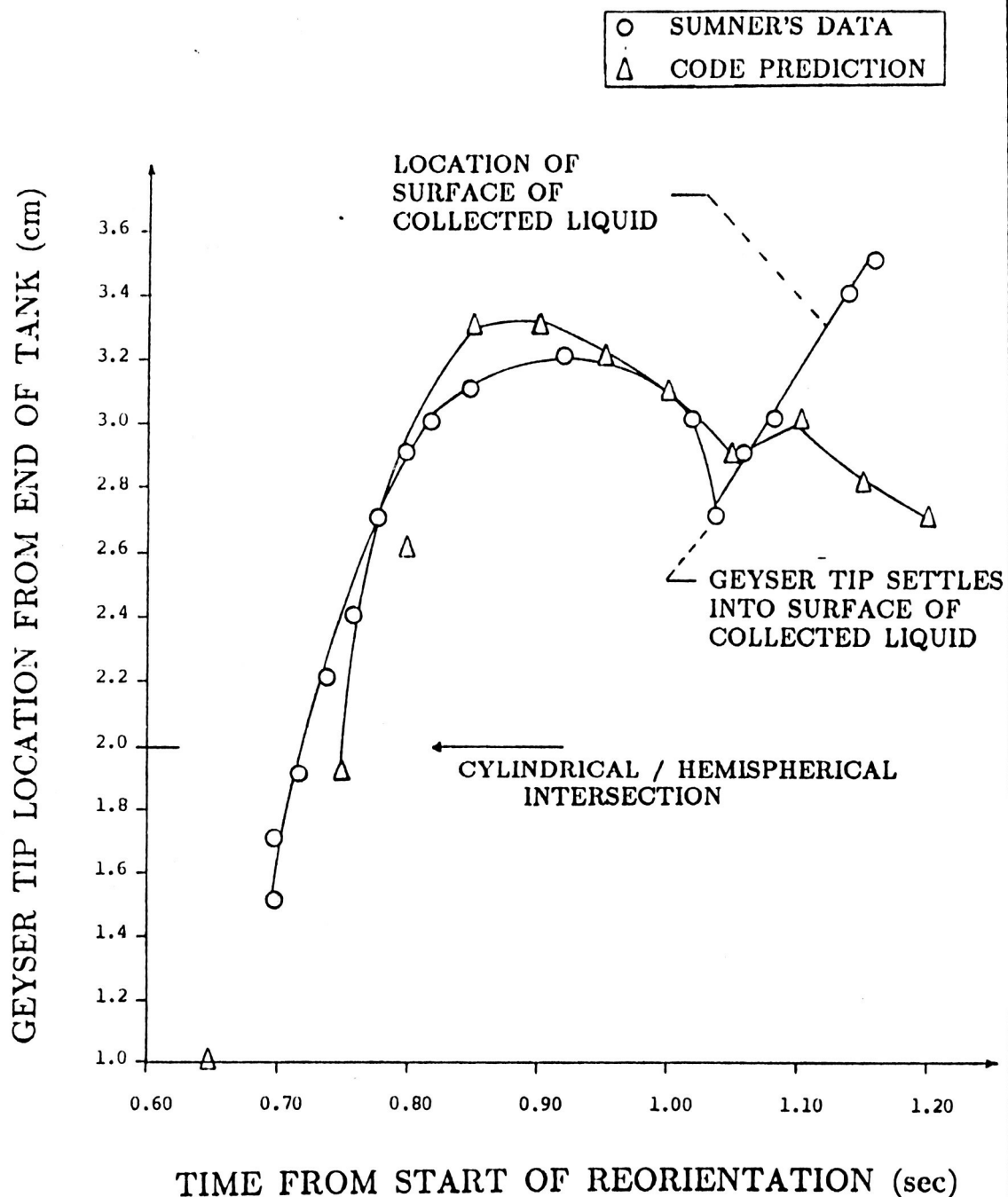
CODE VERIFICATION

8/27

TEST 5



TEST 5: GEYSER TIP LOCATION

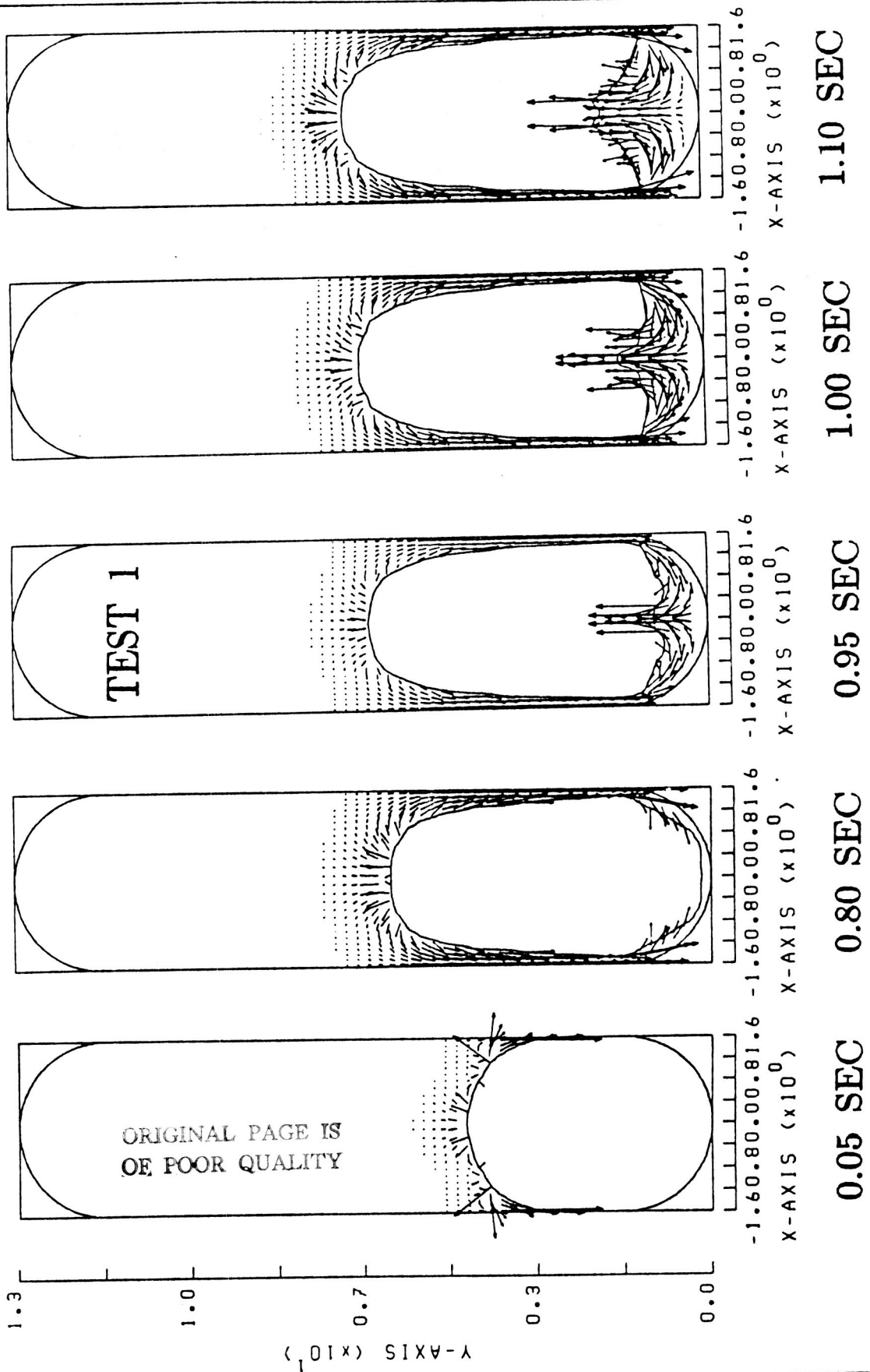




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CODE VERIFICATION

10/27

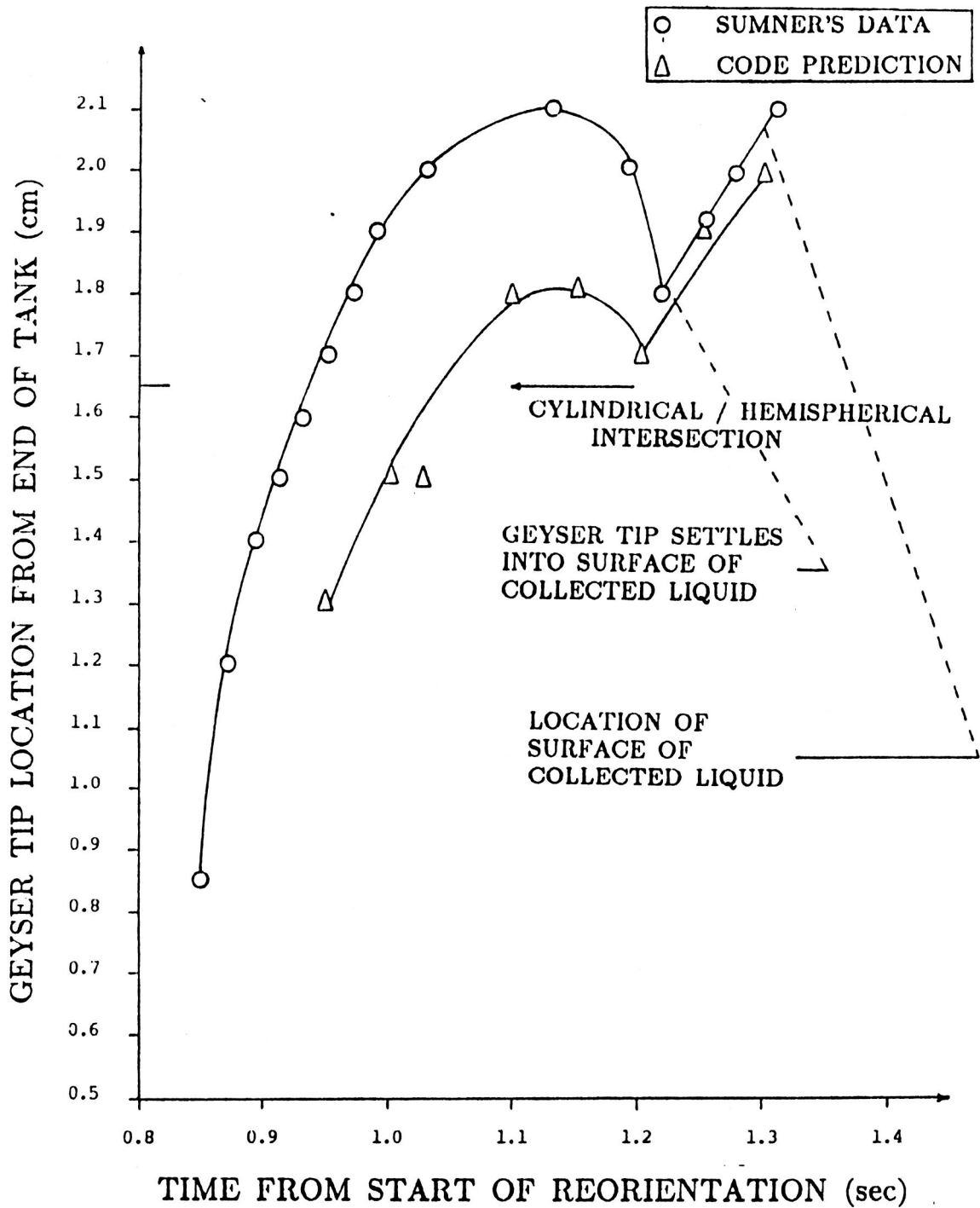


11/27

CODE VERIFICATION



TEST 1: GEYSER TIP LOCATION

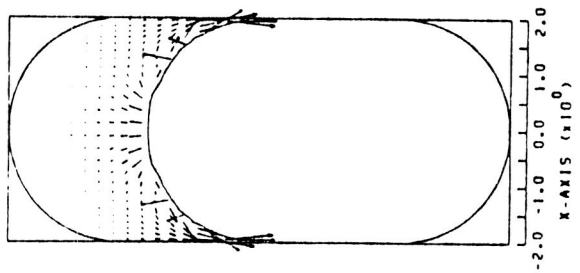
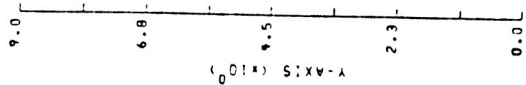




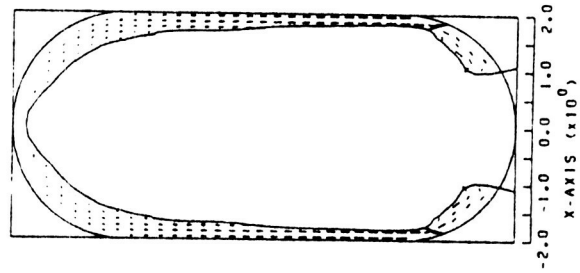
CODE VERIFICATION

12/27

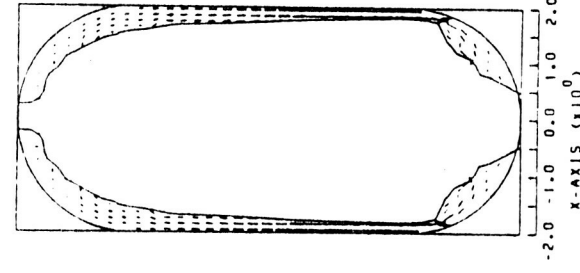
TEST 8



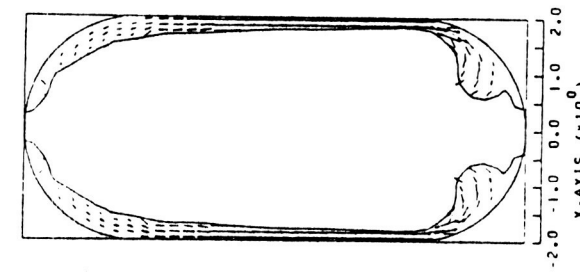
0.05 SEC



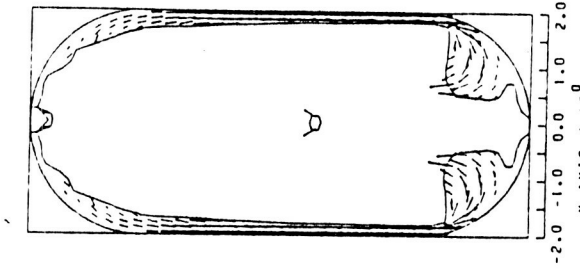
0.80 SEC




0.85 SEC




0.75 SEC



0.90 SEC

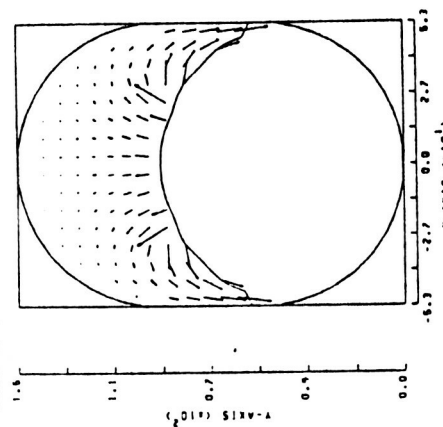
	CODE VERIFICATION	13/27
<p data-bbox="431 643 485 1788"><u>CONCLUSIONS ABOUT CODE PERFORMANCE</u></p> <ul data-bbox="562 296 970 1788" style="list-style-type: none"> <li data-bbox="562 388 731 1788">- AGREEMENT BETWEEN EXPERIMENTAL DATA AND COMPUTATIONAL PREDICTIONS RANGES FROM EXCELLENT TO FAIR. <li data-bbox="808 296 970 1788">- DIFFICULTY WITH SURFACE FOAMING APPEARS IN SOME ANALYSES, REQUIRES FURTHER EVALUATION AND POSSIBLY ALGORITHM MODIFICATION. 		

<div data-bbox="150 1678 243 1882">  </div>	<div data-bbox="166 784 227 1208">REORIENTATION</div> <div data-bbox="181 179 235 302">14/27</div> <div data-bbox="320 662 381 1289">PULSED SETTLING</div> <div data-bbox="420 1535 466 1786"> <p><u>CONCEPT</u></p> </div> <div data-bbox="505 273 713 1786"> <p>REPLACE A CONSTANT THRUST (ACCELERATION) LEVEL WITH INTERMITTENT PULSED ACCELERATIONS TO IMPROVE EFFICIENCY AS MEASURED BY PROPELLANT CONSUMPTION.</p> </div> <div data-bbox="797 1201 851 1786"> <p><u>SPECIFIC CASE STUDY</u></p> </div> <div data-bbox="882 329 1044 1786"> <p>CFMFE: PRIOR TO TANK-TO-TANK LIQUID TRANSFER, THE LIQUID IN THE SUPPLY TANK MUST BE POSITIONED OVER THE OUTLET.</p> </div> <div data-bbox="1067 380 1228 1684"> <p>PROBLEM: ACCELERATION IMPARTED BY FIRING SHUTTLE RCS THRUSTERS FAR EXCEEDS OPTIMAL LEVEL</p> </div> <div data-bbox="1259 819 1313 1684"> <p>SOLUTION: PULSED OPERATION?</p> </div>
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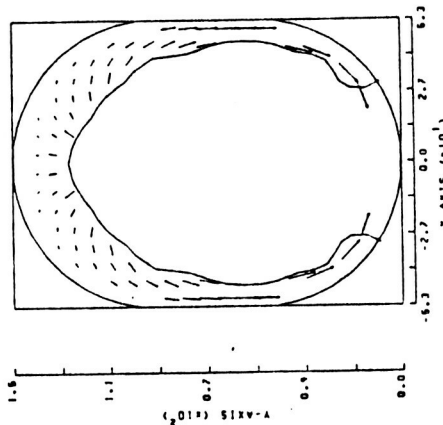


15/27

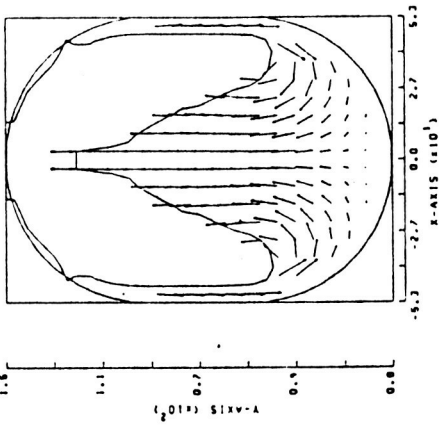
PREDICTIONS FOR 1/4 SCALE CFMFE TANK



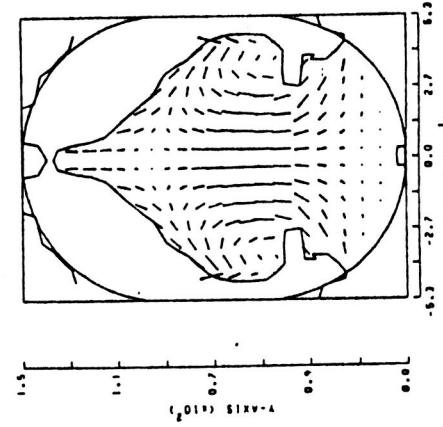
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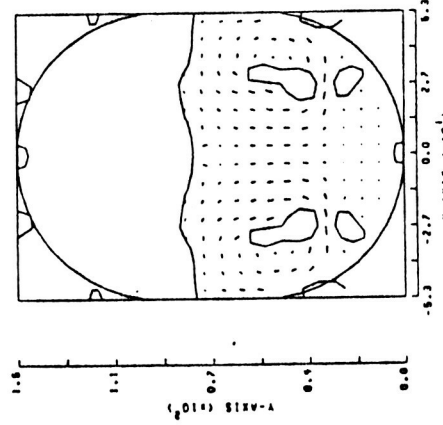
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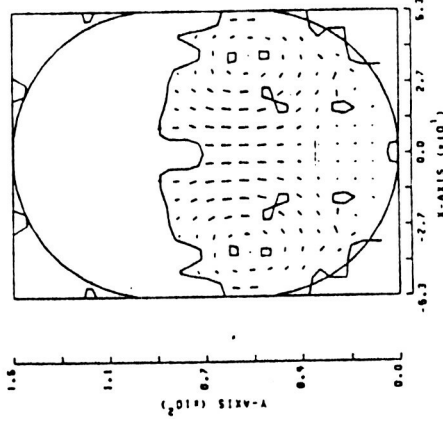
8.00 SEC



12.0 SEC

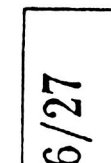


16.0 SEC



20.0 SEC

A = 0.008g's

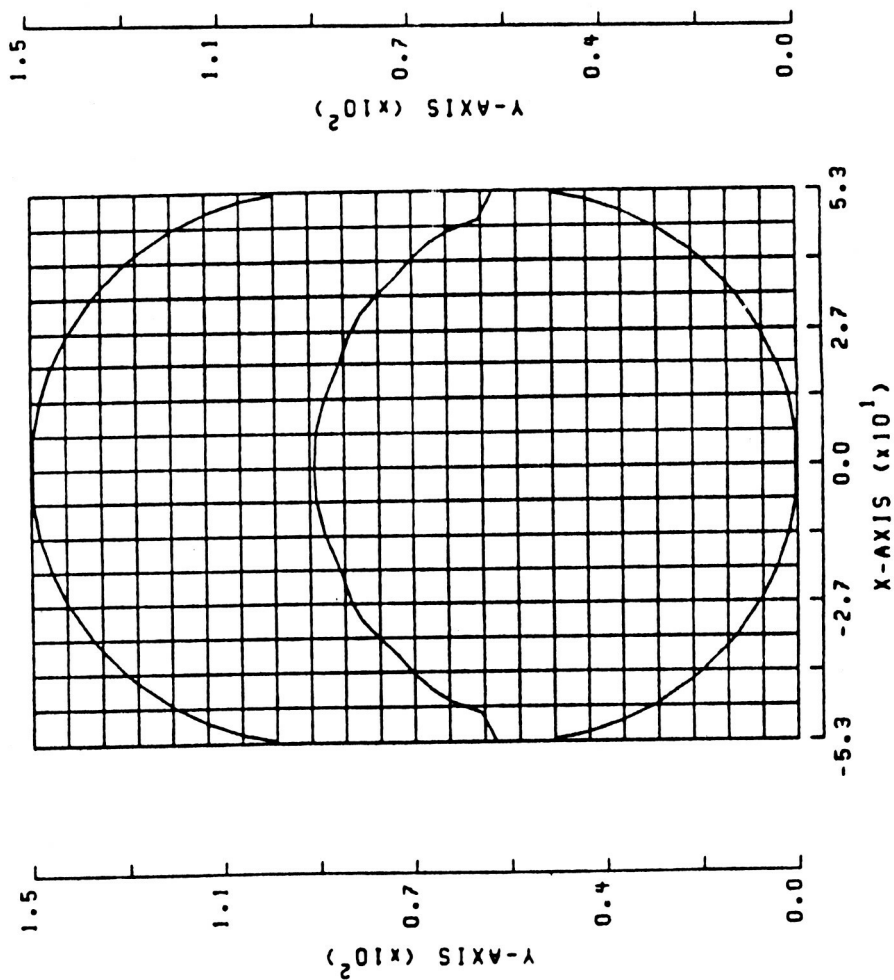
	REORIENTATION	16/27
	<p>PARAMETERS WHICH GOVERN OR DESCRIBE PULSED SETTLING PERFORMANCE.</p> <ul style="list-style-type: none"> -SETTLING TIME -PULSE FREQUENCY -PULSE MAGNITUDE -PULSE DURATION -PROPELLANT CONSUMPTION <p>SUMNER'S CORRELATION WAS USED TO PREDICT AN OPTIMAL STEADY ACCELERATION FOR REORIENTING THE LIQUID IN THE CFMFE.</p> <p>ACCELERATION = 0.036 CM/SEC = 0.000037 g's</p> <p>SETTLING TIME = 63 SECONDS</p> <p>VEHICLE DELTA V = 2.3 CM/SEC</p>	



PREDICTIONS FOR 1/4 SCALE CFMFE TANK

17/27

OPTIMAL STEADY ACCELERATION (SUMNER)



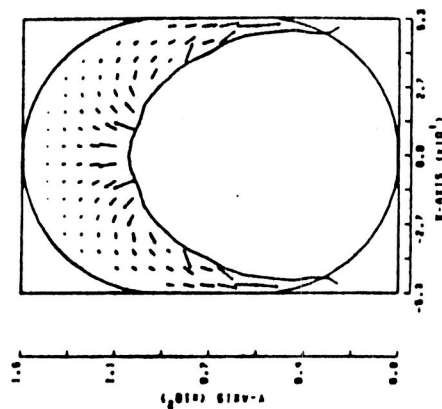
COMPUTATIONAL MESH

0.01 SEC

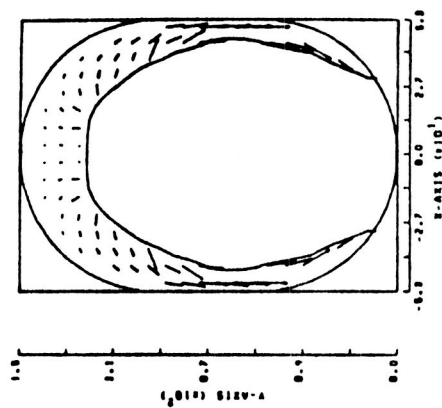


PREDICTIONS FOR 1/4 SCALE CFMFE TANK

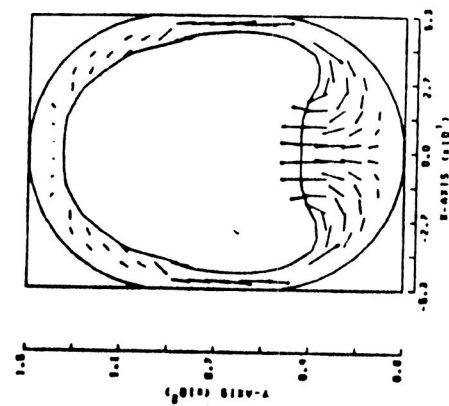
18/27



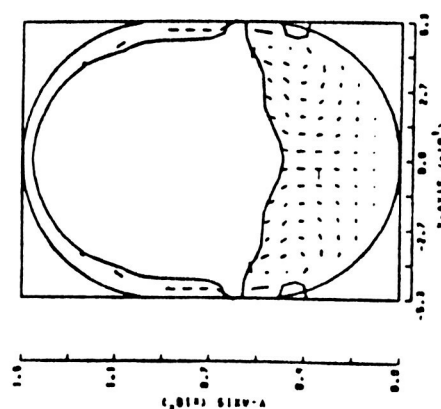
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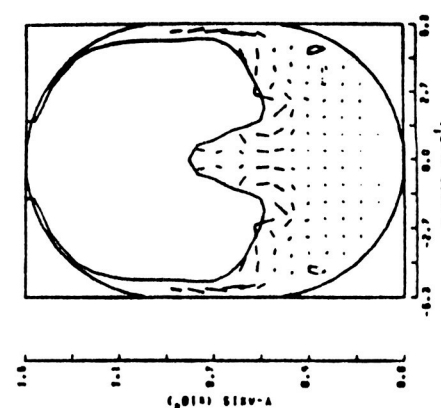
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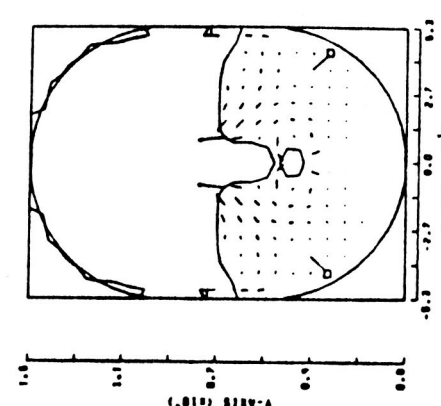
90.0 SEC



121. SEC




150. SEC



180. SEC

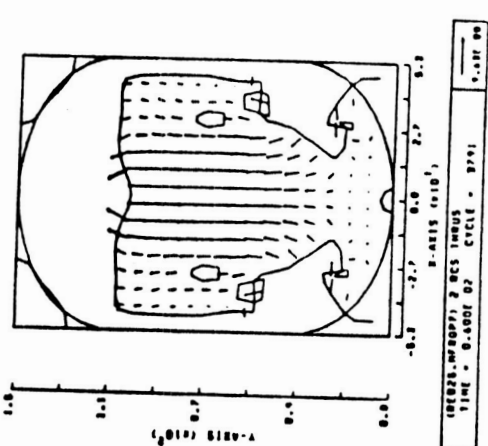
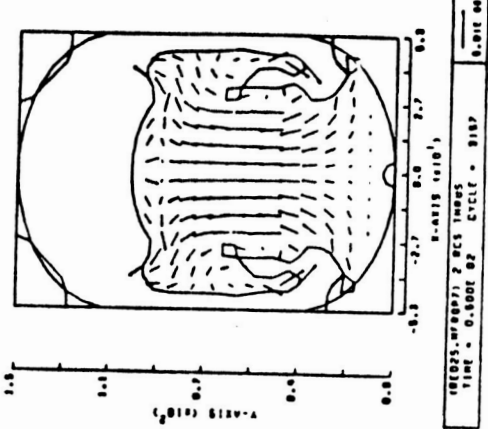
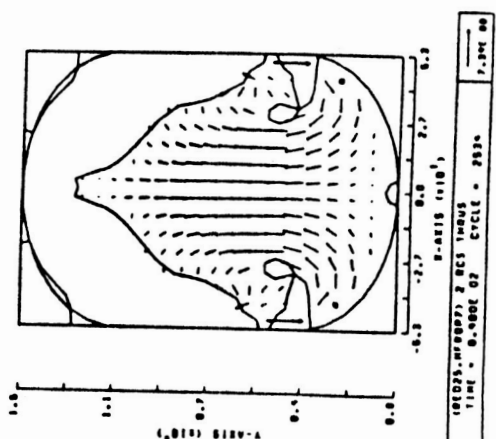
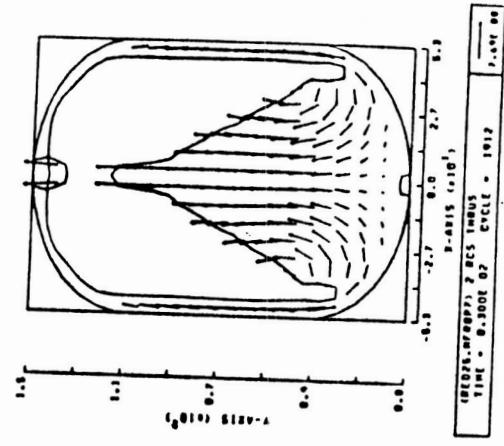
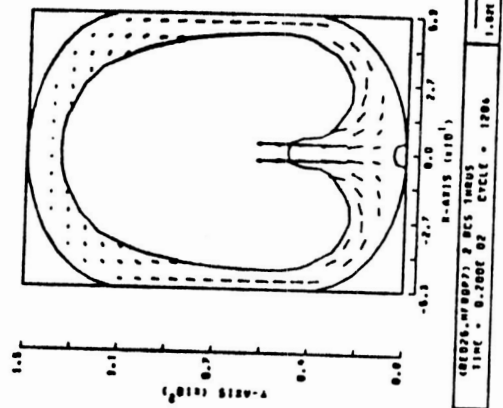
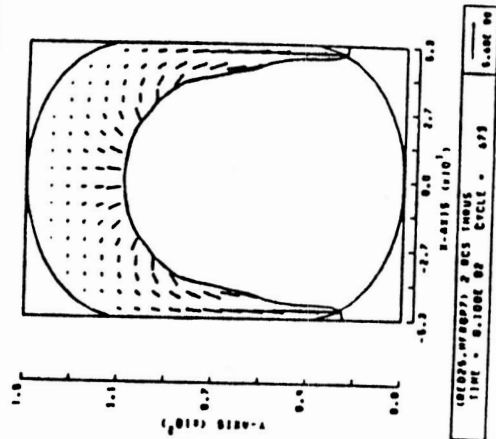
OPTIMAL STEADY ACCELERATION (SUMNER)

	PULSED SETTLING	19/27														
<p>PARAMETER VALUES USED IN PRELIMINARY STUDY</p> <table><tr><td>TANK.....</td><td>CFMFE 25%</td></tr><tr><td>FILL.....</td><td>50% FULL</td></tr><tr><td>BACKGROUND ACCEL.....</td><td>ZERO</td></tr><tr><td>FLUID.....</td><td>LIQUID HYDROGEN</td></tr><tr><td>PULSE MAGNITUDE.....</td><td>0.008g's (2 RCS)</td></tr><tr><td>PULSE FREQUENCY.....</td><td>0.1 - 1.5 Hz</td></tr><tr><td>PULSE DURATION.....</td><td>0.1 & 0.2 SEC</td></tr></table> <p>PROPELLANT IS CONSIDERED SETTLED WHEN THE DISTANCE BETWEEN THE FREE SURFACE AT THE TANK CENTERLINE AND THE OUTLET EXCEEDS 20% OF THE TOTAL TANK LENGTH.</p>			TANK.....	CFMFE 25%	FILL.....	50% FULL	BACKGROUND ACCEL.....	ZERO	FLUID.....	LIQUID HYDROGEN	PULSE MAGNITUDE.....	0.008g's (2 RCS)	PULSE FREQUENCY.....	0.1 - 1.5 Hz	PULSE DURATION.....	0.1 & 0.2 SEC
TANK.....	CFMFE 25%															
FILL.....	50% FULL															
BACKGROUND ACCEL.....	ZERO															
FLUID.....	LIQUID HYDROGEN															
PULSE MAGNITUDE.....	0.008g's (2 RCS)															
PULSE FREQUENCY.....	0.1 - 1.5 Hz															
PULSE DURATION.....	0.1 & 0.2 SEC															



PULSED SETTLING

20/27



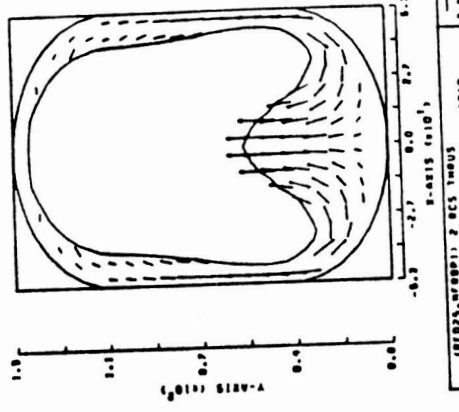
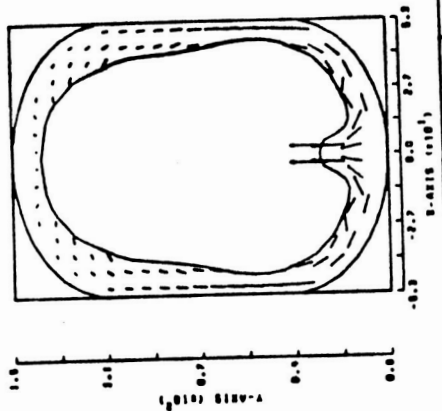
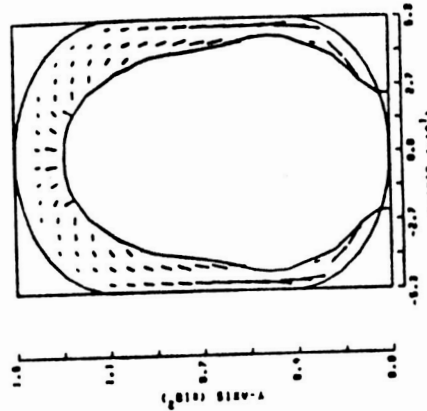
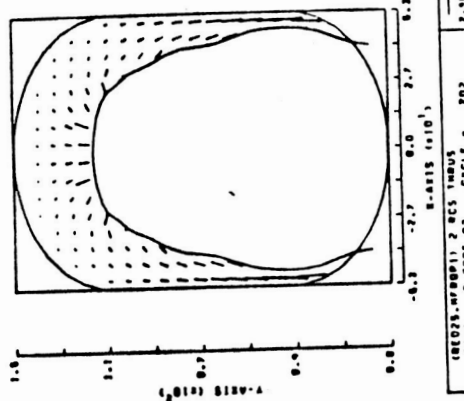
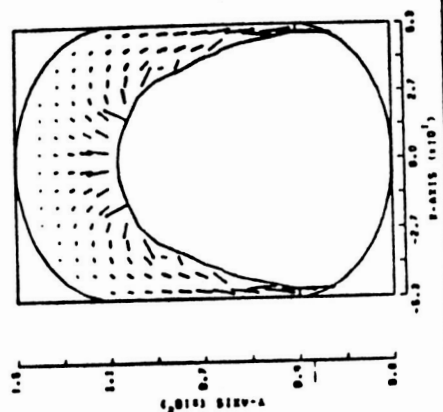
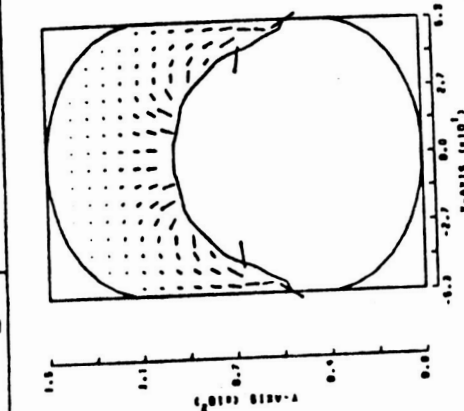
DURATION = 0.1 sec

FREQUENCY = 0.7 HZ



PULSED SETTLING

21/27



DURATION = 0.1 sec

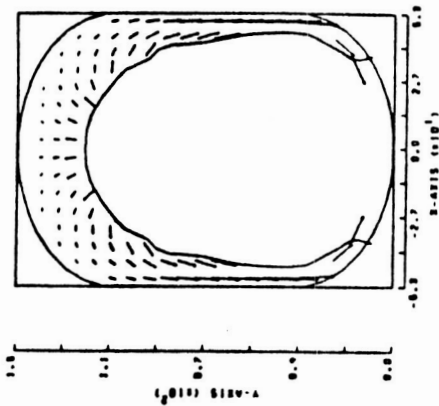
FREQUENCY = 0.1 Hz

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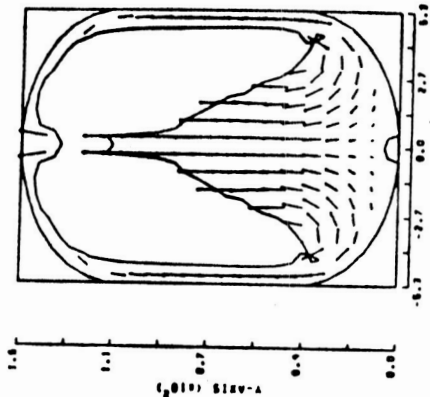


PULSED SETTLING

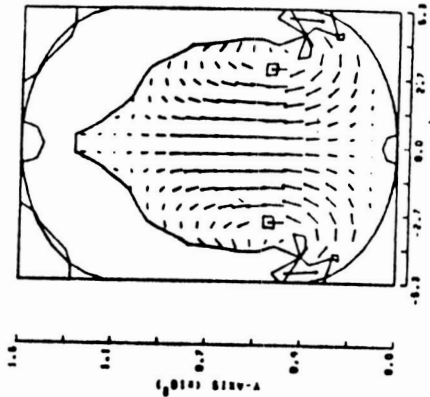
22/27



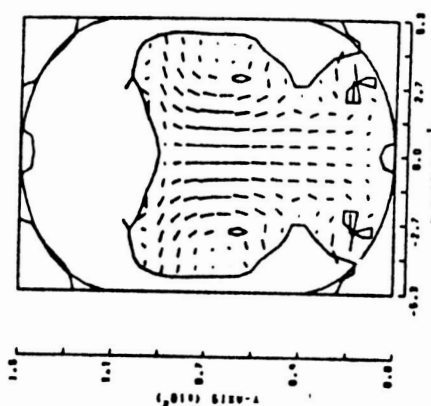
(DEQ25.MF00100) 2 RCS THRU
TIME = 0.000E 02 CYCLE = 050 0.00E 00



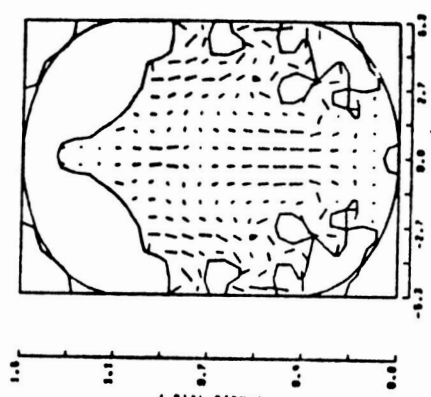
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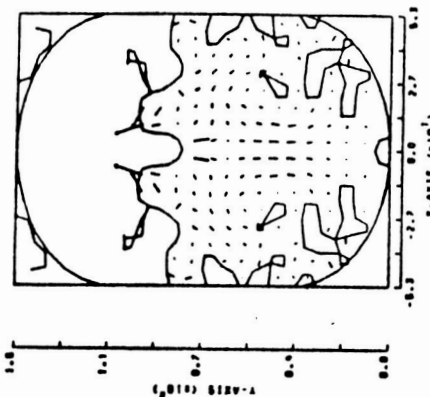
(DEQ25.MF00100) 2 RCS THRU
TIME = 0.800E 02 CYCLE = 2000 1.00E 01



(DEQ25.MF00100) 2 RCS THRU
TIME = 0.900E 02 CYCLE = 2200 0.01E 00



(DEQ25.MF00100) 2 RCS THRU
TIME = 0.600E 02 CYCLE = 9000 1.00E 00

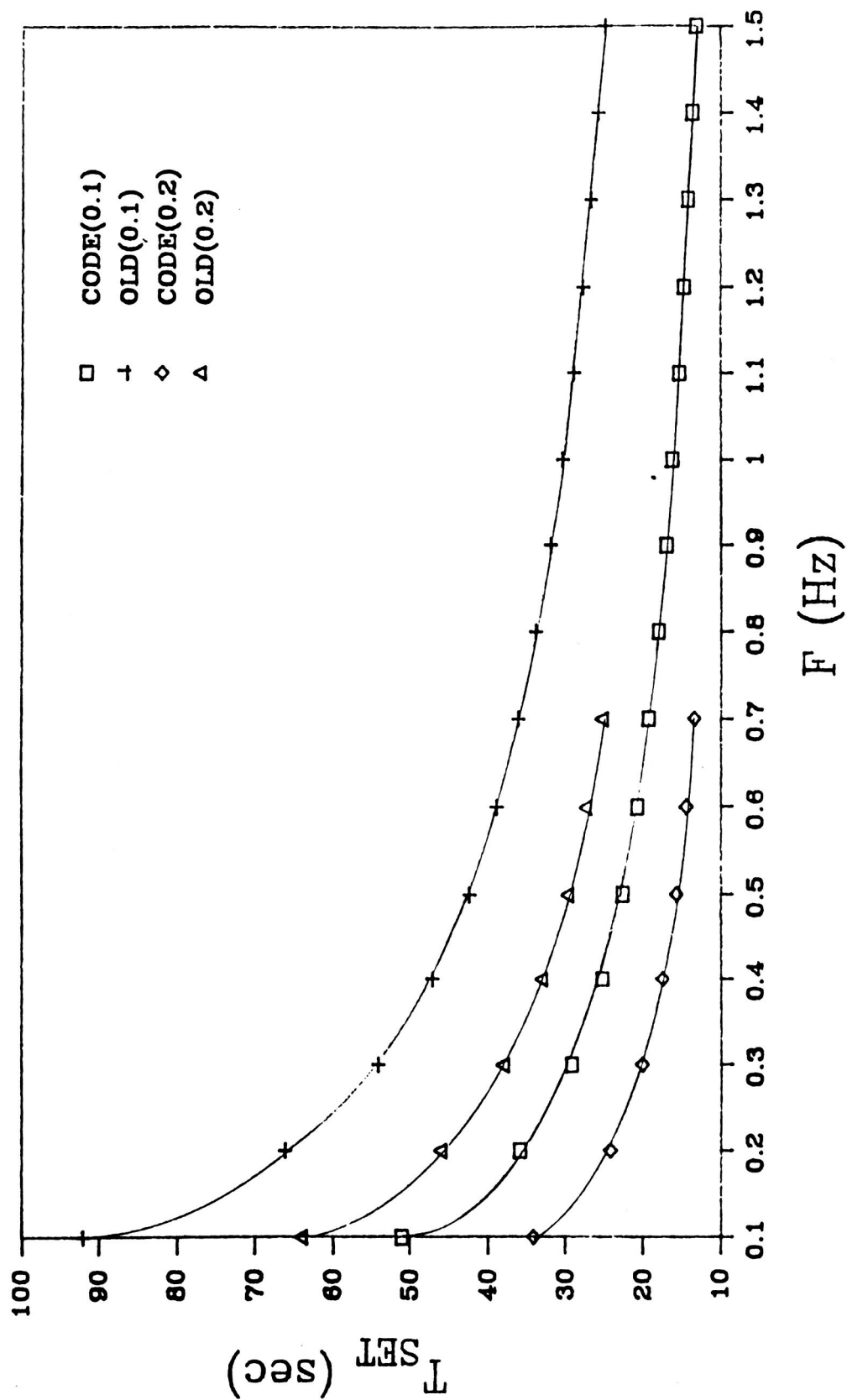


(DEQ25.MF00100) 2 RCS THRU
TIME = 0.000E 02 CYCLE = 0000 0.00E 00

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DURATION = 0.1 sec FREQUENCY = 1.4 Hz

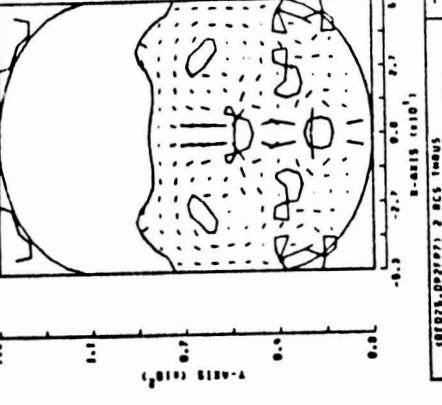
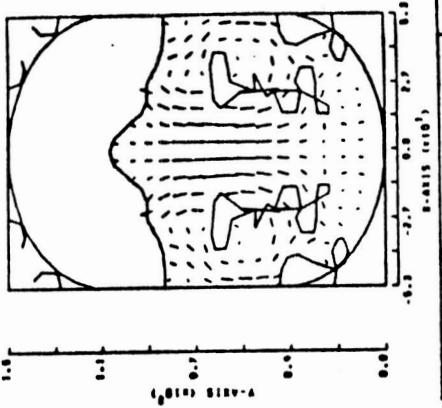
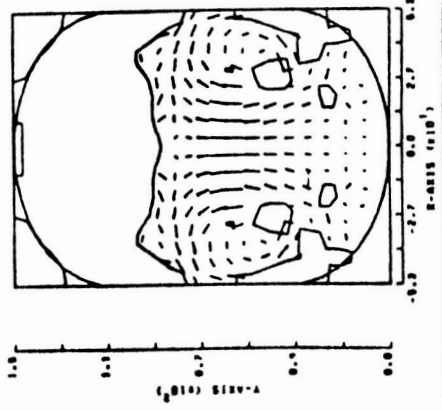
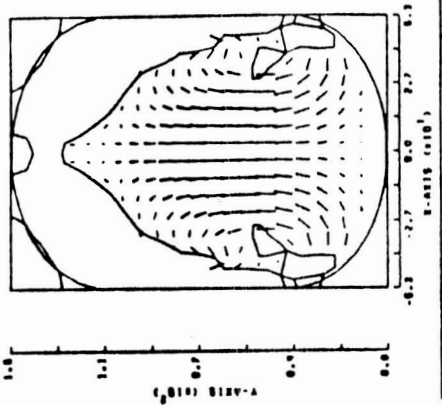
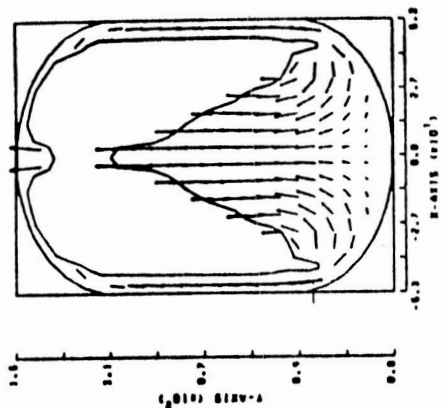
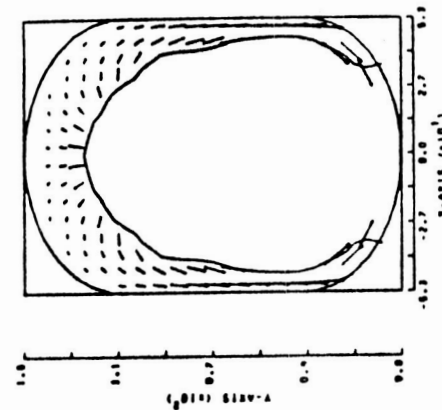
SETTLING TIME .vs. FREQUENCY





PULSED SETTLING

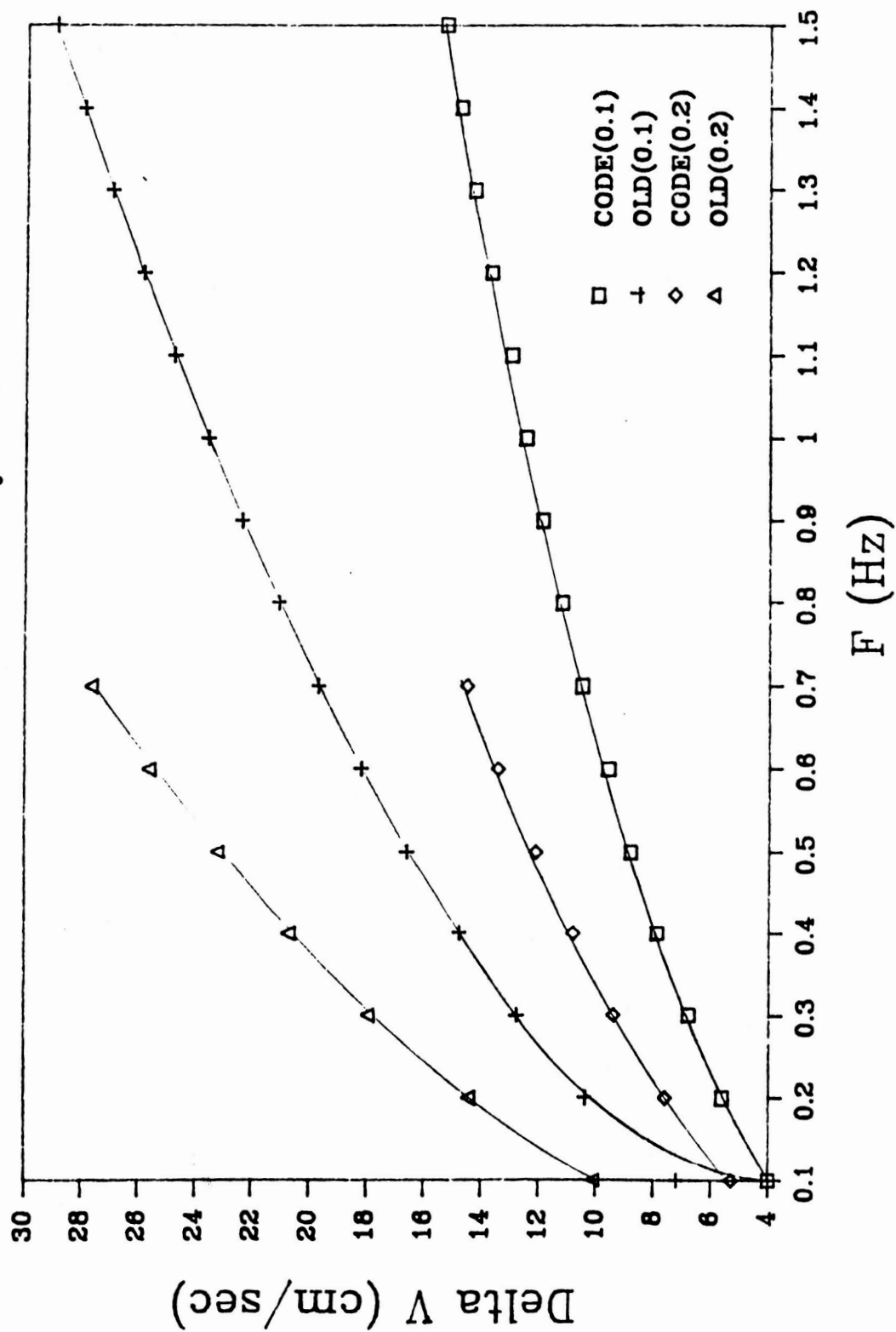
23/27

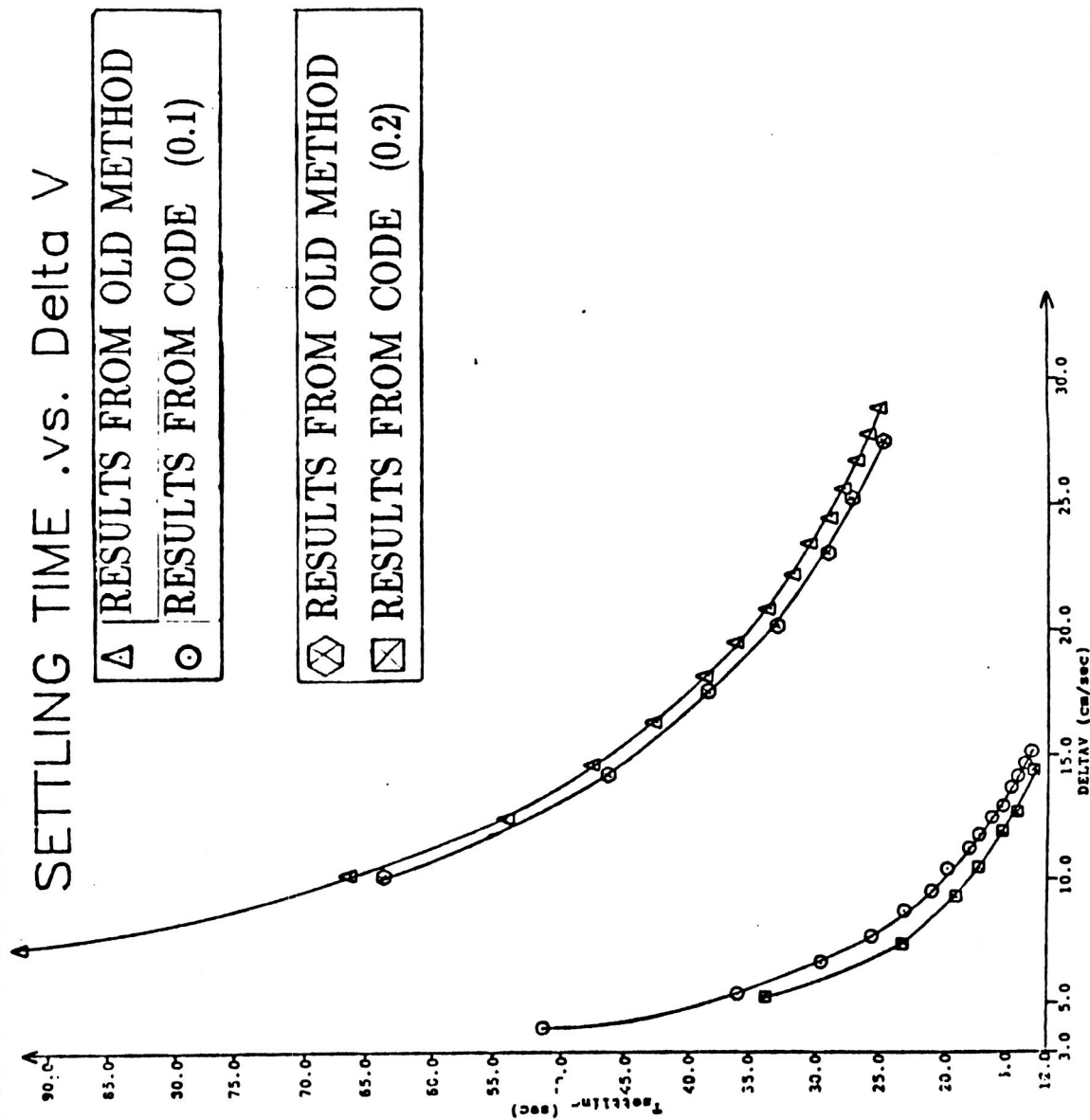



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DURATION = 0.2 sec FREQUENCY = 0.7

Delta V .vs. FREQUENCY





	CONCLUDING REMARKS	27/27
<p data-bbox="368 681 429 1294" style="text-align: center;">PLANED EFFORTS</p> <ul style="list-style-type: none"> <li data-bbox="550 427 716 1782">- STUDY SURFACE FOAMING PROBLEM UNCOVERED DURING VERIFICATION PHASE. MODIFY ALGORITHM IF NECESSARY. <li data-bbox="792 374 1003 1782">- EXPAND PRELIMINARY STUDY INTO A FULL RANGE PARAMETER STUDY OF PULSED SETTLING IN A TYPICAL ORBIT TRANSFER VEHICLE PROPELLANT TANK. 		

SPEAKER: JOHN I. HOCHSTEIN/WASHINGTON UNIVERSITY

James J. Der/Aerospace Corporation:

Did you compare your result with results from the FLOW-3D or HYDR-3D codes, particularly on the foaming problem?

Hochstein:

No we haven't. As you know, the three dimensional codes are more complex, so you get considerably more computational expenses to do that. One of the differences between that code and what we are working with is that the free surface, both the free surface algorithm which works the VOF function, which moves the volume of fluid around, is a little more sophisticated in this code and the surface tension model is considerably more detailed. In FLOW-3D, there would be a substantial computational expense in three dimensions to compute that. What I will say is that when we worked with an earlier version of SOLA-VOF, the mixing problem I alluded to did not have surface foaming in it. That is another reason why we are reasonably convinced it is a computational problem which we haven't identified yet.

Robert S. Rudlin/Martin Marietta Denver Aerospace:

The problem I think you are trying to model is one where you've settled the liquid and then you either drain the liquid out the bottom or you take the gas out the top. This means you could very easily have a boiling situation or you could have bubbles entrained in the outflow, which is a three dimensional problem. Are you planning on doing work in that area in the future so you could understand the draining problem without getting gas in the liquid or the venting problem without getting boiling and liquid going out your vents?

Hochstein:

That is certainly the direction we would like to head. Some of the ongoing work that Lewis is sponsoring is doing things like developing heat transfer and thermodynamic capabilities for this code. As far as the 3-D versus the 2-D effects, I think we can do some good work with the 2-D code before we move on to a 3-D code if we just keep the vents and outlets on the axis. That is work that we intend to do.